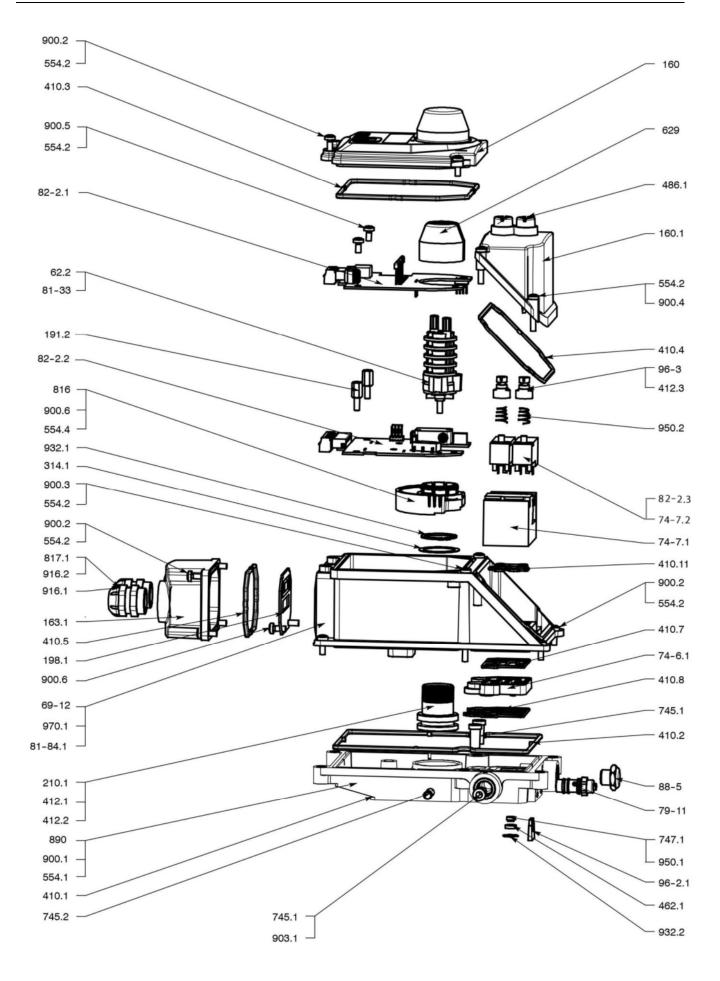
# **AMTRONIC AS-i R1300**



AMTRONIC R1300 AS- i can be fitted directly on all the range ACTAIR/DYNACTAIR pneumatic actuators, and for any type of VDI / VDE pneumatic actuator by external pipe.









Itom	Designation	Materials	
Item	Designation		
160	Cover	Polycarbonate SM60/0	
160.1	Distributor cover	Polycarbonate SM60/0	
163.1	Bonnet	Polycarbonate SM60/0	
191.2	Bonnet	Nickel plate brass	
198.1	Connection plate		
210.1	Shaft	Polycarbonate SM60/0	
314.1	Friction washer	Stainless steel 304L	
410.1	Profile joint	NBR 70	
410.2	Profile joint	NBR 70	
410.3	Profile joint	NBR 70	
410.4	Profile joint	NBR 70	
410.5	Profile joint	NBR 70	
410.7	Profile joint	NBR 70	
410.8	Profile joint	NBR 70	
410.11	Profile joint	NBR 70	
412.1	Profile joint	NBR 70	
412.2	O-ring	NBR 70	
412.3	O-ring	NBR 70	
462.1	Conical washer		
486.1	Ball	Steel	
554.1	Washer	Stainless steel	
554.2	Washer	Stainless steel	
554.4	Safety device	Steel	
62.2	Sub- unit adjustable cam	Oteci	
629	Sub- unit pointer		
69- 12	Case	Polygorhonoto SM60/0	
		Polycarbonate SM60/0	
74- 6.1	Distribution plate		
74- 7.1	Pneumatic valve		
74- 7.2	Pilot		
745.1	Filter	D	
745.2	Filter	Bronze	
747.1	Profile joint check valve		
79- 11	Flow control 1/8"		
81- 33	Detection plate	Steel	
81- 84.1	Wiring diagram		
816	Sub- unit angle sensor		
817.1	Packing gland		
82- 2.1	Printed circuit board		
82- 2.2	Printed circuit board		
82- 2.3	Printed circuit board electro valve		
88- 5	Silencer	Bronze	
96- 2.1	Padlockable plate	Polycarbonate SM60/0	
96- 3	Manual override	Polycarbonate SM60/0	
890	Base	Polycarbonate SM60/0	
900.1	Screw	A2- 70	
900.2	Screw	A2- 70	
900.3	Screw	A2- 70	
900.4	Screw	A2- 70	
900.5	Screw	A2- 70	
900.6	Screw	A2- 80	
903.1	Plug		
916.1	Screwed plug		
916.2	Protection plug	Rubber	
932.1	Circlip	Steel	
932.2	Self- locking retainning ring	Steel	
950.1	Valve spring	0.001	
950.2	Lockable override spring	Stainless steel	
970.1	Identity plate	Adhesive polyester	
310.1	ισοπιιγ μαισ	TUITESIVE PULYESIEI	



Warnings



**CAUTION!** 

Installation and commissioning of the electropneumatic actuators must be carried out in accordance with instrumentation professional standards, and in particular:

#### Piping:

When commissioning a new or modified installation, the piping must be blown through before connecting the actuator in order to clear the circuit of any impurities, which cannot be avoided during construction (iron filings, scale, Teflon, welding flux, etc.).

**Electric wiring:** The power supply voltage and the value of the control signal must be checked before final connection.

#### AMTRONIC R001300 box:

The cover and housing of the unit must be properly closed to protect the contents from humidity and, generally, from the outer atmosphere ("aggressive" atmosphere, dust, etc.) and any incidents which could damage the internal parts.

#### Connection by cable gland:

When the electric connection is made through a cable gland, make sure that:

- the cable gland is suitable for the cable diameter
- the cable gland is correctly tightened on the cable
- if just one of the 2 cable glands is used, replace the unused cable gland with a watertight plug or seal the cable gland

The pneumatic connection must be made according to the product specifications. (see IV-1Pneumatic connection)

## Never exceed the values indicated in this manual!

This box is an electrical device which contains pressurized gas components. As such, it can present a danger for property, or even personnel. Exceeding the values shown can cause damage.

Never uncouple or disassemble the AMTRONIC unit or its accessories when pressurized or powered.

Always make sure that the actuator reservoirs are decompressed by actioning the push- buttons on the pilot emergency controls before disassembling the distributor, its solenoid valves or the unit itself. Also, always check that the power supply cables are disconnected from their source before dismantling.

During workshop or on-site verifications, the valve associated with the actuator and its AMTRONIC unit shall be operated from full opening to full closing position.

This operation may be a highly significant injury hazard for personnel if the safety steps required are not taken to prevent access between the disc and the seat.



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### I - Introduction

## I - 1 General

The AMTRONIC is especially suited to any ½ turn VDI/VDE 3845 pneumatic actuator in particular the ACTAIR 3 to 200 series and DYNACTAIR 1.5 to 100 thanks to direct pneumatic distribution (without piping).

#### Command control functions

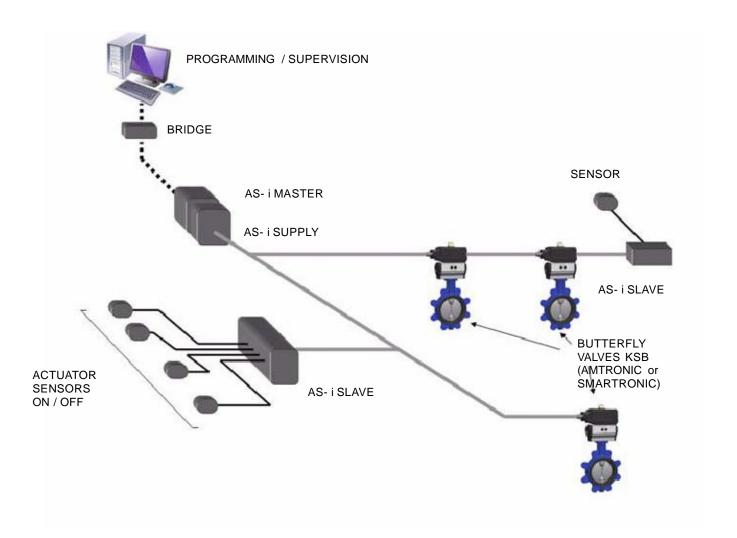
All versions of this box include the following electrical and pneumatic functions:

- On/off position detection using switches or proximity detectors,
- Pneumatic distribution by built in electro distributor (4 ports/2 positions or 4/ports/3 positions),
- Adjustment of open and close operating time, by air flow limiter on the exhaust. Different options can be mounted on the unit and are included in this notice.

## I - 2 The AS-i (Actuator Sensor-Interface) network

It is a Master/Slave type network: The PLC (master) receives control and sends cyclically the controls to each slave. This simple and robust network, mainly in the case of SMARTRONIC box, only uses the 2- wire cable to provide the power supply and carry the digital control data.

- The various parts of AS- i network:
  - Slaves including AS- i module for input/output
  - AS- i power supply.
  - Master AS- i (PLC) for the control and monitoring of slaves.

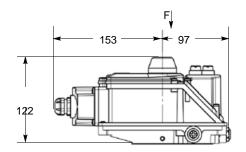


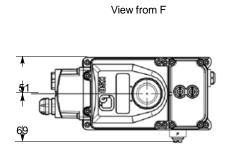


## I - 3 Technical characteristics

Environment	
Standard protection class	IP 67 according to EN 60529
Electromagnetic Compatibility	Complies with European directive CEM 2004/108/EC in accordance with NF EN 61000- 6- 2 and NF EN 61000- 6- 4
Climatic class	<ul> <li>Storage temperature: - 30 °C to + 80 °C</li> <li>Working temperature: - 20 °C to + 80 °C</li> </ul>
Vibrations	- According to IEC 68- 2- 6 Test Fc
Box	
Material	PC 20% Fiberglass
Position signaling	By visible pointer on the cover
Pneumatic connection	2 times 1/4" gas
Electric connection	- by 2 M20 metallic or plastic cable glands for cable ø 6 to 12 mm,
Internal connectors	<ul> <li>Length to be stripped:7 mm</li> <li>Cross- section of rigid or flexible conductor: 0.14mm² to 1.5 mm²</li> <li>Cross- section of flexible conductor with end connector without insulating entry cone: 0.25 mm² to 1.5 mm²</li> <li>Cross- section of flexible conductor with end connector with insulating entry cone: 0.25 mm² to 0.5 mm²</li> </ul>
Weight	1,70 Kg
Pneumatic distribution	
Pressure connection	Port 1/4" gas marked "P" equipped with an internal filter
Exhaust connection	Port 1/4" gas marked "E" equipped with a silencer or connectable to exhaust network
Operating pressure	3 to 8 bar (44 to 115 psi)
Filtration level	ISO 8573- 1 class 7 (< 40 μm)
Dew point	ISO 8573- 1 class 5 (<7 °C and in all cases <5 °C at ambient temperature)
Lubrication	ISO 8573- 1 class 5 (< 25mg/m <sup>3</sup> )
Maximum flow rate	400 NI/min
Consumption when idle	none
AS- i network	
Electric consumption	150 mA (maximum)
Electric supply	By AS- i network (26.5 VDC to 31.5 VDC)
Profile	S- 3.0 or S- B.A.E
Maximum quantities of slaves	31 (profile S- 3.0) or 62 (profile S- B.A.E)

# Dimensions (mm)

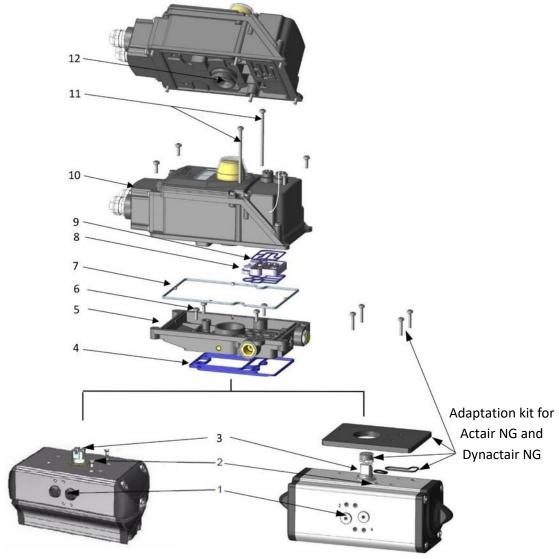






## II - Assembly on pneumatic actuator

# II - 1 ACTAIR 3 to 200, ACTAIR NG 2 to 160, DYNACTAIR 1.5 to 100 and DYNACTAIR 1 to 80



- A- Check that the actuator has both plugs (item 1) on the external supply holes.
- B- Remove the two screws with seals (item 2) (TORX T20 screwdriver).
- C- Separate the unit (item 10) from the base (item 5) by unscrewing the 6 screws (item 11) (TORX T20 screwdriver).
- D- Remove distribution plate A or B (item 8) with both gaskets, item 9.
- E- Attach the base (item 5) to the actuator with the 4 screws (item 6) (TORX T20 screwdriver). Tightening torque = 2.5 Nm



Check the correct position of the seal, item 4.

F- Reposition distribution plate A or B (item 8) with its two seals, item 9



Check the correct position of the seal, item 9.

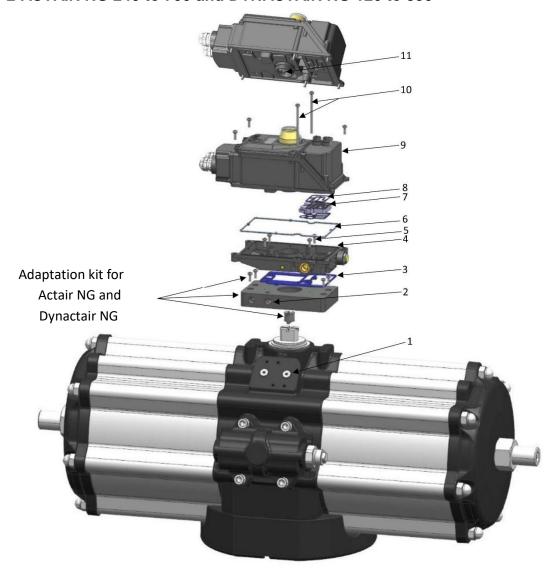
G- Position the unit (item 10) on the base (item 5) taking care to engage the column (item 12) with the actuator shaft (item 3) and tighten the 6 M4 screws (item 11) (TORX T20 screwdriver).



Check the correct position of the seal, item 7.



## II - 2 ACTAIR NG 240 to 700 and DYNACTAIR NG 120 to 350



- A- Position the adaptations elements for Actair NG and Dynactair NG
- B- Fix the adapter kit plate to the actuator interface with 4 M5 screws
- C- Separate the unit (item 9) from the base (item 4) by unscrewing the 6 screws (item 10) (TORX T20 screwdriver).
- D- Remove distribution plate A or B (item 7) with its two seals (item 5).

E- Fix the base (item 4) to the actuator using 4 M5 screws + seals + washers (item 5) (TORX T20 screwdriver). Tightening torque = 2.5 Nm



Check the correct position of the seal (item 3).

F- Reposition distribution plate A or B (item 7) with its two seals (item 8).



Check the correct position of the seal (item 8).

G- Position the unit (item 9) on the base (item 4) taking care to engage the column (item 11) with the adapter and tighten the 6 M4 screws (item 10) (TORX T20 screwdriver).



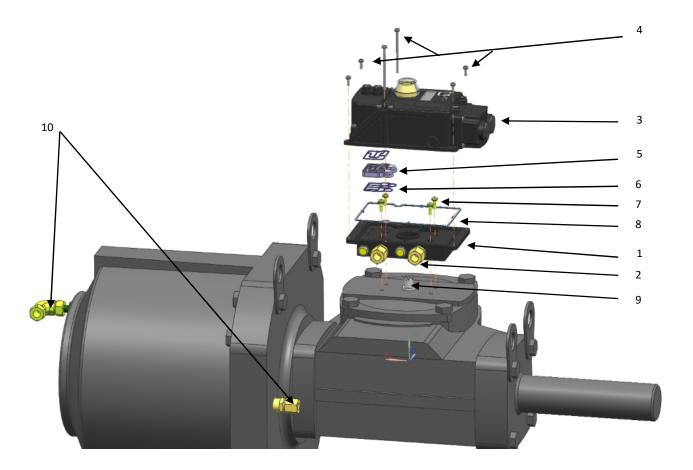
Check the correct position of the seal (item 6).



## II - 3 ACTAIR 400 to 1600 and DYNACTAIR 200 to 800 and other 1/4 turn actuators



These instructions only relate to pneumatic  $\frac{1}{2}$  turn actuators whose flange complies with VDI/VDE 3845 with the following dimensions: A = 80 mm; B = 20 mm (actuator shaft height). For the other VDI/VDE dimensions, please contact us.



- A Check that the base (item 1) supplied with the unit is intended for this type of actuator. It must have two ¼" gas pneumatic openings (item 2 connections not supplied) on the side, to supply the actuator chambers).
- B Separate the unit (item 3) from the base (item 1) by unscrewing the 6 M4 screws (item 4) (TORX T20 screwdriver).
- C Remove distribution plate A or B (item 5) with its two seals (item 6)
- D Fix the base (item 1) to the actuator using 4 M5 screws + seals + washers (item 7) (TORX T20 screwdriver)
- E Reposition distribution plate A or B (item 5) with its two seals (item 6)

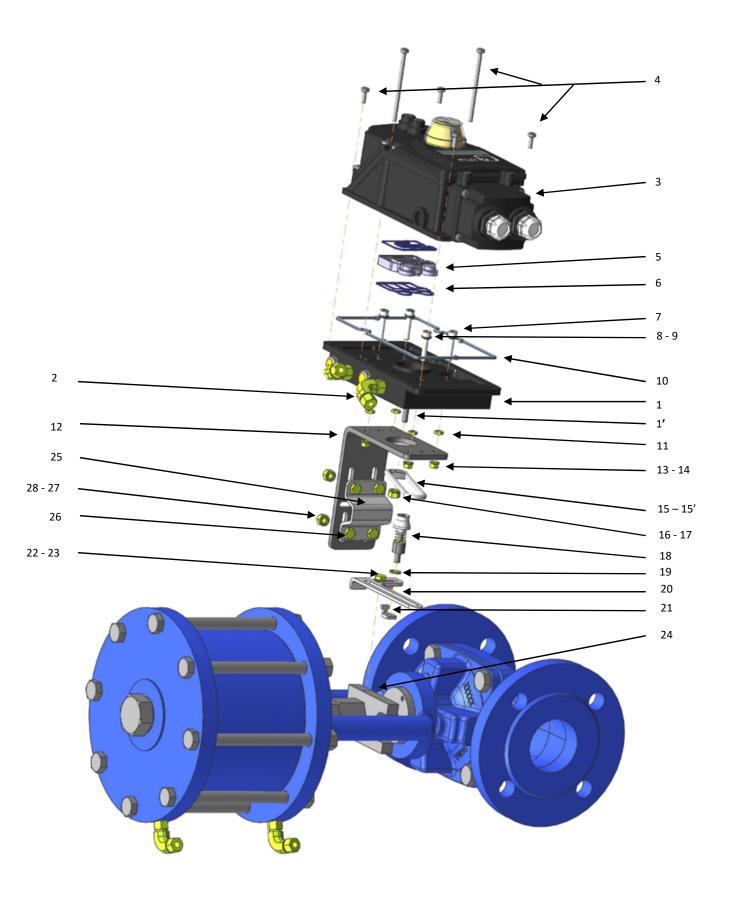


Check that the seal is correctly positioned (item 8)

- F Position the unit (item 3) on the base (item 1) taking care to engage the white shaft of the unit with the shaft (item 9) of the actuator and tighten the 6 M4 screws (item 4) (TORX T20 screwdriver)
- G-The openings of the base  $(2 \times \%'' G)$  (item 2) must be connected to the pneumatic actuator (item 10) as shown in the actuator instructions.



## II - 3 Linear actuators







These instructions only relate to linear pneumatic actuators which comply with VDI/VDE 3847 with rod-shaped pillars: For the other actuator types, please contact us.

A – Check that the base (item 1) supplied with the unit is intended for this type of actuator. It must have two  $\frac{1}{4}$ " gas pneumatic openings (item 2 - connections not supplied) on the side, to supply the actuator chambers).

- B Separate the unit (item 3) from the base (item 1) by unscrewing the 6 M4 screws (item 4) (TORX T20 screwdriver).
- C Remove distribution plate A or B (item 5) with its two seals (item 6)
- D Fit a washer (item 9) and an O-ring (item 8) on each of the 4 M5 screws (item 7)
- E Tighten these 4 screws onto the base (item 1) with the 4 low-profile nuts (item 11)
- F Fix the base (item 1) to the plate (item 12) by tightening the 4 screws (item 7) and the washers (item 13) and nuts (item 14)



The base can be positioned every 180° according to requirements/ constraints

- G Mount the fluted rivet (item 15') on the driver (item 15). Mount the unit onto the shaft (item 1') and tighten with the nut (item 17) and washer (item 16)
- H Reposition distribution plate A or B (item 5) with its two seals (item 6)



Check that the seal is correctly positioned (item 10)

- I Position the unit (item 3) on the base (item 1) taking care to engage the white shaft of the unit with the shaft (item 1) of the base and tighten the 6 M4 screws (item 4) (TORX T20 screwdriver)
- J-Mount the sub-assembly (item 18) fitted with the washer (item19) on the plate (item 20) by tightening it onto the counterplate (item 21)
- K Fix the assembled plate (item 20) onto the valve slider (item 24) with the screws (item 22) and washers (item 23).
- L Fix the plate (item 12) to one of the actuator pillars using the plate (item 25) by tightening the 4 screws (item 26) and the washers (item 27) and nuts (item 28)

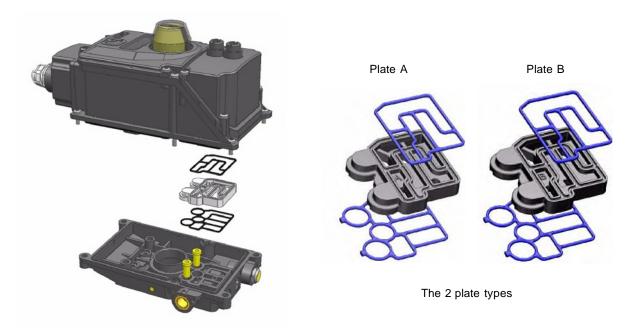


Adjust the position of the plate (item 12) and the sub-assembly (item 18) so that the sub-assembly (item 18) slides in the driver (item 15) (without exiting) over the entire valve stroke.



## III - Safety position on loss of current

The safety position on loss of current of the AMTRONIC is configured in the factory according to the order. It can be modified by changing the distribution plate (Plate A or B) or by changing the type of the solenoid valves 4/3 center closed.



Position of the plate A or B

Depending on the plate used (A or B) and depending on the actuator size, we obtain different safety positions on loss of current.

#### - Distributor monostable

	Safety position on loss of current		
Actuator	Plate A	Plate B	
ACTAIR 3 to 200 (End-stops on closing)	Closing	Opening	
ACTAIR NG 2 to 160 (End-stops on closing	Closing	Closing	
ACTAIR 3 to 200 (End-stops on opening)	Opening	Closing	
ACTAIR NG 2 to 160 (End-stops on opening)	Opening	Closing	
DYNACTAIR 1.5 to 25 (Air fail close)	Closing		
DYNACTAIR 1.5 to 25 (Air fail open)	Opening		
DYNACTAIR 50 and 100 (Air fail close)		Closing	
DYNACTAIR NG 1 to 80 (Air fail close)		Closing	
DYNACTAIR 50 and 100 (Air fail open)		Opening	
DYNACTAIR NG 1 to 80 (Air fail open)		Opening	

Other actuators: plate A

#### - Distributor bistable

Always plate A.

In case of power failure, the box remains in the last commanded position (open or closed).



### - Distributor 4/3 center closed

Always plate B.

The safety position in case of power failure is defined by the type of solenoid valve NO (Normally Open) or NC (normally closed).

	Safety position on loss of current		
Actuator	EV1 (NC) EV2 (NC)	EV1 (NO) EV2 (NC)	EV1 (NC) EV2 (NO)
ACTAIR 3 to 200 (End-stops on closing)	STOP	Closing	Opening
ACTAIR NG 2 to 160 (End-stops on closing)	STOP	Closing	Opening
ACTAIR 3 to 200 (End-stops on opening)	STOP	Opening	Closing
ACTAIR NG 2 to 160 (End-stops on opening)	STOP	Opening	Closing
DYNACTAIR 1.5 to 25 (Air fail close)	STOP	Closing	Opening
DYNACTAIR 1.5 to 25 (Air fail open)	STOP	Opening	Closing
DYNACTAIR 50 and 100 (Air fail close)	STOP	Opening	Closing
DYNACTAIR NG 1 to 80 (Air fail close)	STOP	Opening	Closing
DYNACTAIR 50 and 100 (Air fail open)	STOP	Closing	Opening
DYNACTAIR NG 1 to 80 (Air fail open)	STOP	Closing	Opening



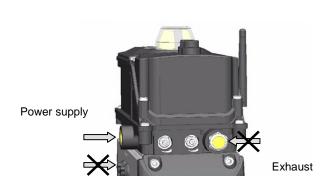
## IV - Pneumatic supply

## IV - 1 Pneumatic connection

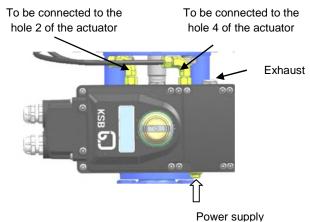
Before making any pneumatic connections, check that there are no impurities in the piping, especially when starting the installation. As a measure of safety, the box is equipped with a filter in the input port in order to prevent the clogging of the distributor with impurities.

This filter can be cleaned: remove and clean it with solvent or compressed air.

#### **Direct pneumatic connection**



### Pneumatic connection by piping



- The connection is made on the AMTRONIC box
- Operating pressure: 3 to 8 bar (44 to 115 psi)
- Pressure connection: hole "P"
- Exhaust connection: port marked "E" equipped with a silencer or connectable to an exhaust network.

Caution: To avoid any premature wear of mechanical parts, particularly for the actuator, it is recommended to use a lubricated air (between 5 and 25 mg/m<sup>3)</sup>.

Attention: If severe vibrations are expected or excessive tensile strain (max. 80 kg) needs to be prevented at the ¼" gas thread connections, the use of flexible tubing is strongly recommended for pneumatic connection.



## IV - 2 Mechanical adjustment of the operating time

It is possible to adjust the valve operating time by actioning the screws at the base of the box.

### Procedure:

Adjust the adjustment screws depending on the type of actuator used (see figure below).

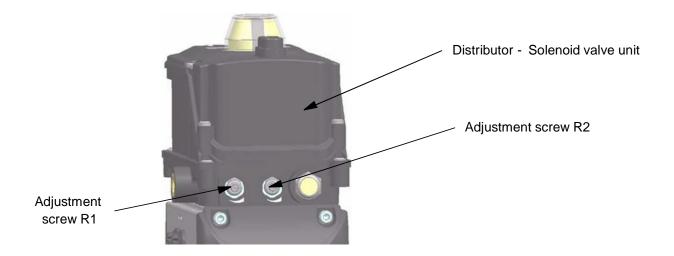
Double-acting actuators				
Туре	Min. operating time			
ACTAIR 3	1 second			
ACTAIR 6	1 second			
ACTAIR 12	2 seconds			
ACTAIR 25	4 seconds			
ACTAIR 50	5 seconds			
ACTAIR 100	6 seconds			
ACTAIR 200	9 seconds			
ACTAIR 400	25 seconds			
ACTAIR 800	50 seconds			
ACTAIR 1600	90 seconds			

Double-acting actuators				
Туре	Min. operating time			
ACTAIR NG 2	1 second			
ACTAIR NG 5	1 second			
ACTAIR NG 10	1 second			
ACTAIR NG 15	2 seconds			
ACTAIR NG 20	2 seconds			
ACTAIR NG 30	2 seconds			
ACTAIR NG 40	3 seconds			
ACTAIR NG 60	3 seconds			
ACTAIR NG 80	5 seconds			
ACTAIR NG 120	7 seconds			
ACTAIR NG 160	9 seconds			
ACTAIR NG 240	17 seconds			
ACTAIR NG 340	18 seconds			
ACTAIR NG 500	30 seconds			
ACTAIR NG 700	40 seconds			
	<u> </u>			

Single-acting actuators					
Туре	Min. operating time				
DYNACTAIR 1.5	2 seconds				
DYNACTAIR 3	2 seconds				
DYNACTAIR 6	2 seconds				
DYNACTAIR 12	4 seconds				
DYNACTAIR 25	6 seconds				
DYNACTAIR 50	10 seconds				
DYNACTAIR 100	15 seconds				
DYNACTAIR 200	45 seconds				
DYNACTAIR 400	90 seconds				
DYNACTAIR 800	180 seconds				

Single-acting actuators				
Type	Min. operating time			
DYNACTAIR NG 1	1 second			
DYNACTAIR NG 2	1 second			
DYNACTAIR NG 4	1 second			
DYNACTAIR NG 6	3 seconds			
DYNACTAIR NG 8	3 seconds			
DYNACTAIR NG 12	4 seconds			
DYNACTAIR NG 16	6 seconds			
DYNACTAIR NG 25	8 seconds			
DYNACTAIR NG 35	11 seconds			
DYNACTAIR NG 50	16 seconds			
DYNACTAIR NG 80	23 seconds			
DYNACTAIR NG 120	14 seconds			
DYNACTAIR NG 160	16 seconds			
DYNACTAIR NG 240	27 seconds			
DYNACTAIR NG 350	37 seconds			





ACTAIR 3 to 200 and ACTAIR NG 2 to	160	R1	R2
Stop on closing (standard version)		Closing time	Opening time
Stop on opening (upon request)		Opening time	Closing time
DYNACTAIR 1.5 to 100 and DYNACTAIR NG 1 to 80	Safety position on loss of pneumatic	R1	R2
DYNACTAIR 1.5 to 25	Closed	Closing time	Opening time
DYNACTAIR 50 and 100	Open	Closing time	Opening time
DYNACTAIR NG 1 to 80	Open		
DYNACTAIR 1.5 to 25	Open	On an in a time	Clasing times
DYNACTAIR 50 and 100	Closed	Opening time	Closing time
DYNACTAIR NG 1 to 80	Closed		



## V - Electric connections

## V - 1 General

L'AMTRONIC is shipped with 2 IP67 plugs.



To access the electrical connection terminals, unscrew the 4 TORX screws (T20) from the connection housing.

Tightening torque: 2Nm

Connection on unpluggable connector:

- Length to be stripped: 7 mm
- Cross- section of rigid or flexible conductor: 0.14mm<sup>2</sup> to 1.5 mm<sup>2</sup>
- Cross- section of flexible conductor with end connector without insulating entry cone: 0.25 mm<sup>2</sup> to 1.5 mm<sup>2</sup>
- Cross- section of flexible conductor with end connector with insulating entry cone: 0.25 mm<sup>2</sup> to 0.5 mm<sup>2</sup>

#### Cable gland (option):

- 2 M 20 plastic cable glands (polyamide) for cable ø 6 to 12,
- 2 M 20 metallic cable glands (nickel- plated brass) for cable Ø 7 to 12.

## V - 2 Connection to the AS- i network







## VI - AS-i communication

Installation on the network varies depending on the type of board (specify when ordering):

- Profile S- 3.0: up to 31 slaves on the AS- i network.
  - 100% compatible with AMTRONIC AS- i first generation.
- Profile S- B.A.E: up to 62 slaves on the AS- i network (extended addressing),
  - 100% compatible with AMTRONIC AS- i v2.11 second generation

## VI - 1 AMTRONIC profile S-3.0

## VI - 1 - 1 Profile of the AS - i slave

The profile of the AS- i slave is 3.0. It complies with AS- i version v2.00, which corresponds to IO = 3 and ID = 0.

The box is delivered with address 0. An address between 1 and 31 must be assigned prior to installation in the network.

This address is stored in non- volatile memory in the AS- i slave circuit. Addressing can be carried out by the master or a specific pocket terminal.

During installation on an AS-i v2.11 network, the following parameters must be entered:  $ID\ 1 = F$  and  $ID\ 2 = F$ .

## VI - 1 - 2 Inputs / Outputs

1/0	Туре	Description	State	Meaning
10	Input	state of the travel limit sensor corres-	0	valve not closed
10	(AMTRONIC)	ponding to the valve closed position	1	valve closed
1.1	Input	state of the travel limit sensor corres-	0	valve not open
''	(AMTRONIC)	ponding to the valve open position	1	valve open
0.2	Output	control of solenoid valve EV 2	0	Non-controlled solenoid valve EV 2
02	(AMTRONIC)	Control of Solenoid Valve EV 2	1	Controlled solenoid valve EV 2
0.3	Output	control of solenoid valve EV 1	0	Non-controlled solenoid valve EV 1
0.3	(AMTRONIC)	Control of Solenoid Valve EV 1	1	Controlled solenoid valve EV 1

For the actions of solenoid valves EV1 and EV2, refer to chapter VII - Pneumatic distribution.



## VI - 2 AMTRONIC profile S-B.A.E

## VI - 2 - 1 Profile of the AS - i slave

The AMTRONIC AS- i slave complies with specification V2.11 and can be configured in an extended addressing mode.

The profile is S- B.A.E (2 inputs and 2 outputs): IO = B, ID = A, ID1 = 7, ID2 = E.

The AMTRONIC slave is delivered with address 0.

The address can be programmed as follows:

- 1 to 31 with an AS- i v2.00 master
- 1A to 31B with an AS- i v2.11 master

## VI - 2 - 2 Inputs / Outputs

I/O	Туре	Description	State	Meaning
12	Input	state of the travel limit sensor corres-	0	valve not closed
12	(AMTRONIC)	ponding to the valve closed position	1	valve closed
13	Input	state of the travel limit sensor corres-	0	valve not open
13	(AMTRONIC)	ponding to the valve open position	1	valve open
0 1	Output	control of solenoid valve EV 2	0	Non-controlled solenoid valve EV 2
01	(AMTRONIC)	Control of Soletiola valve EV 2	1	Controlled solenoid valve EV 2
0 0	Output	control of solenoid valve EV 1	0	Non-controlled solenoid valve EV 1
00	(AMTRONIC)	Control of Solelioid Valve EV 1	1	Controlled solenoid valve EV 1

For the actions of solenoid valves EV1 and EV2, refer to chapter VII - Pneumatic distribution.

## VI - 3 Indication of the box operating status

LEDs fitted on the top of the box indicate the AMTRONIC operation state.



#### Power LED:

- Off: box not powered up
- Lit: box powered up

#### Fault LED:

- Off: communication with an AS- i master
- Lit: no AS- i communication

EV2 LED: state of EV2 control

EV1 LED:\_state of EV1 control

**CLED:** state of closure travel limit

**OLED:** state of opening travel limit



## VII - Pneumatic distribution

## VII - 1 Monostable distributor

A single pilot connected to EV1.

Safety position on loss of electrical supply	EV1=0	EV1=1
Closed	Closed	Open
Open	Open	Closed

### VII - 2 Bistable distributor

The solenoid valve action depends on the valve safety position when the device has no electrical supply and for the type of actuator in application.

#### Case N° 1:

- ACTAIR 3 to 200, end-stops on closing
- ACTAIR NG 2 to 160, end-stops on closing
- DYNACTAIR 1.5 to 25, closing by air failure, end-stops on closing
- DYNACTAIR 50 and 100, opening by air failure, end-stops on opening
- DYNACTAIR NG 1 to 80, opening by air failure, end-stops on opening

EV1=0	EV1=1	EV1=0
EV2=0	EV2=0	EV2=1
Last command	Closed	Open

### Case N° 2:

- ACTAIR 3 to 200, end-stops on opening
- ACTAIR NG 2 to 160, end-stops on opening
- DYNACTAIR 1.5 to 25, opening by air failure, end-stops on opening
- DYNACTAIR 50 and 100, closing by air failure, end-stops on closing
- DYNACTAIR NG 1 to 80, closing by air failure, end-stops on closing

EV1=0	EV1=1	EV1=0
EV2=0	EV2=0	EV2=1
Last command	Open	Closed



## VII - 3 4/3 distributor

The solenoid valve action depends on the valve safety position when the device has no electrical supply and for the type of actuator in application.

#### Case N° 1:

- ACTAIR 3 to 200, end-stops on closing
- ACTAIR NG 2 to 160, end-stops on closing
- DYNACTAIR 1.5 to 25, closing by air failure, end-stops on closing
- DYNACTAIR 50 and 100, opening by air failure, end-stops on opening
- DYNACTAIR NG 1 to 80, opening by air failure, end-stops on opening

Safety position on loss of electrical supply	EV1=0 EV2=0	EV1=1 EV2=0	EV1=0 EV2=1	EV1=1 EV2=1
STOP (stays in position)	STOP (stays in position)	Closed	Open	
Closed	Closed	STOP (stays in position)		Open
Open	Open		STOP (stays in position)	Closed

### Case N° 2:

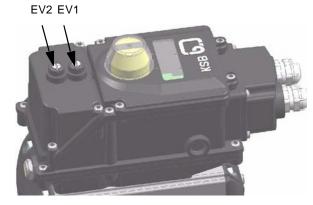
- ACTAIR 3 to 200, end-stops on opening
- ACTAIR NG 2 to 160, end-stops on opening
- DYNACTAIR 1.5 to 25, opening by air failure, end-stops on opening
- DYNACTAIR 50 and 100, closing by air failure, end-stops on closing
- DYNACTAIR NG 1 to 80, closing by air failure, end-stops on closing

Safety position on loss of electrical supply	EV1=0 EV2=0	EV1=1 EV2=0	EV1=0 EV2=1	EV1=1 EV2=1
STOP (stays in position)	STOP (stays in position)	Open	Closed	
Closed	Closed		STOP (stays in position)	Open
Open	Open	STOP (stays en position)		Closed

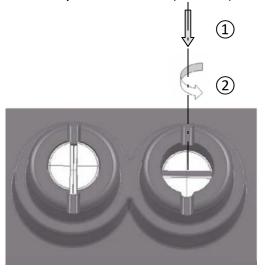


## VII - 4 Use of emergency manual controls

External emergency controls can be used to operate the solenoid valves manually.



To avoid any interference with the solenoid valve electrical controls, it is recommended that emergence controls only be used when the product is powered off.



EV2 = 0 EV1 = 1

The emergency controls are fitted with a locking mechanism. Pour activer une commande de secours :

- 1 Push the emergency control
- (2) Rotate through 90° to lock into position.

## Monostable distributor

A single manual emergency control on EV1.

Its action is inverse to the valve safety position on loss of electrical supply.

Safety position on loss of electrical supply	EV1=0	EV1=1
Closed	Closed	Open
Open	Open	Closed



## Bistable distributor

#### Case N° 1:

- ACTAIR 3 to 200, end-stops on closing
- ACTAIR NG 2 to 160, end-stops on closing
- DYNACTAIR 1.5 to 25, closing by air failure, end-stops on closing
- DYNACTAIR 50 and 100, opening by air failure, end-stops on opening
- DYNACTAIR NG 1 to 80, opening by air failure, end-stops on opening

EV1=0	EV1=1	EV1=0
EV2=0	EV2=0	EV2=1
Last command	Closed	Open

#### Case N° 2:

- ACTAIR 3 to 200, end-stops on opening
- ACTAIR NG 2 to 160, end-stops on opening
- DYNACTAIR 1.5 to 25, opening by air failure, end-stops on opening
- DYNACTAIR 50 and 100, closing by air failure, end-stops on closing
- DYNACTAIR NG 1 to 80, closing by air failure, end-stops on closing

EV1=0	EV1=1	EV1=0
EV2=0	EV2=0	EV2=1
Last command	Open	Closed

### 4/3 distributor

#### Case N° 1:

- ACTAIR 3 to 200, end-stops on closing
- ACTAIR NG 2 to 160, end-stops on closing
- DYNACTAIR 1.5 to 25, closing by air failure, end-stops on closing
- DYNACTAIR 50 and 100, opening by air failure, end-stops on opening
- DYNACTAIR NG 1 to 80, opening by air failure, end-stops on opening

Safety position on loss of electrical supply	EV1=0 EV2=0	EV1=1 EV2=0	EV1=0 EV2=1			
STOP (stays in position)	STOP (stays in position)	Closed	Open			
Closed	Emergency manual controls not available					
Open	— Emergency manual controls not available					

## Case N° 2:

- ACTAIR 3 to 200, end-stops on opening
- ACTAIR NG 2 to 160, end-stops on opening
- DYNACTAIR 1.5 to 25, opening by air failure, end-stops on opening
- DYNACTAIR 50 and 100, closing by air failure, end-stops on closing
- DYNACTAIR NG 1 to 80, closing by air failure, end-stops on closing

Safety position on loss of electrical supply	EV1=0 EV2=0	EV1=1 EV2=0	EV1=0 EV2=1			
STOP (stays in position)	STOP (stays in position)	Open	Closed			
Closed	Emergency manual controls not available					
Open	Lilleigei	Emergency manual controls not available				

## Warnings



**CAUTION** 

After using the emergency controls, remember to return the 2 controls to position 0.

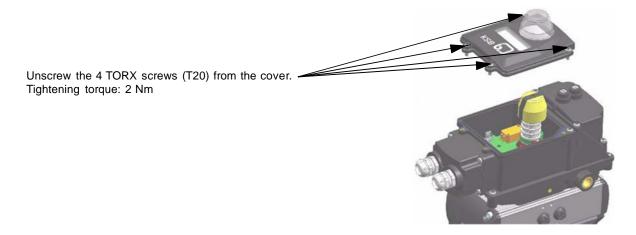
If you do not, the solenoid valve electrical controls will be inactive.



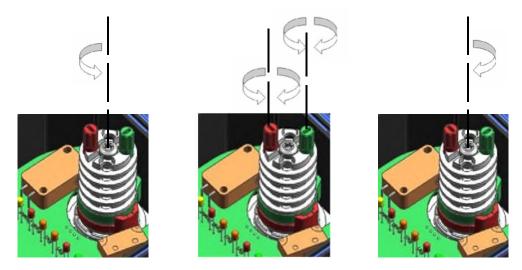
## VIII - Adjusting limit switches or contacts

The cams are preset in the factory. However, it is possible to adjust their positions, in particular if the actuator mechanical stops are modified.

1 - Open the unit housing to access cam adjustment.



- 2 Move the positioner to the end position (O or C).
- 3 Remove the position pointer.
- 4 Loosen the central screw of the cam (Torx screwdriver T20).
- 5 Adjust triggering of the required contact by turning the coloured screw corresponding to the colour of the cam to be adjusted (Red: closing; green: opening).
- 6 Proceed in the same manner with the opposite contact (from step 2).
- 7 Each cam is set independently and has no impact on the setting of the other cams.
- 8 When the settings are finished, tighten the central screw of the cam moderately to lock the settings.





# IX - Operating faults - Causes and solutions

Operating faults	Causes	Corrections
When the valve is closed, limit does not change condition.	The closure detection cam is positioned incorrectly.	- Adjust the cam position.
When the valve is open, limit does not change condition.	The opening detection cam is positioned incorrectly.	- Adjust the cam position.
One or more solenoid valves are activated but the actuator does not move.	- Control of solenoid valves does not conform with the AMTRONIC configuration	Check that the solenoid valve control corresponds to the box configuration (see VII - Pneumatic distribution)
	- Manual control(s) activated	Check that the manual controls are in position 0
	<ul> <li>No air supply</li> <li>Air pressure too high (P &gt; 8 bar).</li> <li>Air pressure too low (P &lt; 3 bar).</li> <li>Valve blocked</li> <li>Actuator blocked or destroyed</li> <li>Distributor obstructed by impurities</li> </ul>	<ul> <li>Check the pneumatic supply.</li> <li>Check and restore pressure P.</li> <li>Check and restore pressure P.</li> <li>Check the freedom of movement of the valve.</li> <li>Change the actuator.</li> <li>Change the inlet filter.</li> </ul>
Operating time too long.	- Brake adjustment too long.	Unscrew the brakes (operating time adjustment)
	<ul><li>Air pressure too high (P &gt; 8 bar).</li><li>Air pressure too low (P &lt; 3 bar).</li></ul>	<ul><li>Check and restore pressure P.</li><li>Check and restore pressure P.</li></ul>
The AS- i AMTRONIC does not communicate with the AS- i master	the AS- i board is not powered up (Power LED off)  Bad profile declared in the master	Check the wiring and voltage of the AS-     i power supply     Check that the profile of the slave declared
	- Bad AS- i addressing.	in the master corresponds to that of the AMTRONIC  - Check that the address AS- i of the slave declared in the master corresponds to that of the AMTRONIC



## X - Codifications

					C	od	ific	at	io	n									Designation
R001300 /													0			6	0	0	Box AMTRONIC
																			Detection
R/	1	0	0	0									0			6	0	0	Microswitche on printed circuit board
R/	2	0	0	0									0			6	0	0	Microswitche on printed circuit board
R/	В	1	1										0	0		6	0	0	Microswitche V3 with wires
R/	В	2	1										0	0		6	0	0	Microswitche V3 with cable
R/	В	3	1										0	0		6	0	0	Microswitche V3 with cable lug 4.8
R/	В	4	1										0	0		6	0	0	Microswitche V3 with cable lug 6.3
R/	В	6	1										0	0		6	0	0	Microswitche V3 terminal to weld
R/	Н	2	1										0	0		6	0	0	Detector V3 PNP with cable 3 wires
R/	Н	2	2										0	0		6	0	0	Detector V3 NPN with cable 3 wires
R/	Н	Α	3										0	0		6	0	0	Detector V3 CC/CA with cable 2 wires
R/	Н	Α	4										0	0		6	0	0	Detector V3 NAMUR with cable 2 wires
R/	Н	3	1										0	0		6	0	0	Detector V3 PNP with 3 cable lugs 4.8
																			Detector V3 CC/CA with 2 cable lugs 4.8
R/	Н	В	4										0	0		6	0	0	Detector V3 NAMUR with 2 cable lugs 4.8
R/	Н	4	1										0	0		6	0	0	Detector V3 PNP with 3 cable lugs 6.3
																			Detector 40x26x12 PNP with cable 3 wires
R/	J	Α	3			0							0	0		6	0	0	Detector 40x26x12 CC/CA with cable 2 wires
																			Detector dia. 6,5 PNP with cable 3 wires
R/	L	2	1			0							0	0		6	0	0	Detector M8 PNP with cable 3 wires
R/	M	2	1			0							0	0		6	0	0	Detector M12 PNP with cable 3 wires
R/	M	Α	3			0							0	0		6	0	0	Detector M12 CC/CA with cable 2 wires
R/	M	Α	4			0							0	0		6	0	0	Detector M12 NAMUR with cable 2 wires
R/	N	Α	4			0							0	0		6	0	0	Detector M14 NAMUR with cable 2 wires
R/	Р	2	1			0							0	0		6	0	0	Detector M18 PNP with cable 3 wires
R/	Р	2	2			0							0	0		6	0	0	Detector M18 NPN with cable 3 wires
R/	Р	Α	3			0							0	0		6	0	0	Detector M18 CC/CA with cable 2 wires
																			Detector M18 NAMUR with cable 2 wires
																			Position detection
R/					1								0			6	0	0	1/O and 1/C
R/																			
R/																			
																			1/O and 1/C and 2/I
																			Feed- back position
R/						0							0			6	0	0	Without feed- back
																			With angle sensor 5kOhm
																			With feed- back 4- 20 mA - Passive (2 wires)
																			With feed- back 20- 4 mA - Passive (2 wires)
																			Electrical output
R/			_				n	)					n			6	Ω	n	2 plastic plugs M20 IP67
																			2 plastic packing glands M20 IP67 (dia. 6 to 12)
1/	٠	•	•	٠	•	٠		•		•	•	•	U	•	•	Ö	U	U	2 metallic packing gland M20 IP67 (dia. 6 to 12)



	n
Pneumatic valve	
R/	
R/	
R/	osition (POS)
Pneumatic valve voltage	
R/	
R/	
R/ 4 0 6 0 0 48 Vac 50/60Hz	
R/	
R/	
R/	osing (F)
R/	= : :
R/	······································
R/	ure (FMA)
R/	· · · · ·
R/	
R/	air failure (FMA)
R/	
R/	
R/	
R/	•
R/	
Fallback position	
R/	
R/	
R/	
R/ Q <b>D</b> 0 6 0 0 Position undefined by current failure (	(PIMC)
Field bus	
R/ 0 <b>0</b> . 6 0 0 Without	
R/ 1 0 7 0 <b>2</b> 0 6 0 0 Profibus DP	
R/ 1 0 7 0 <b>7</b> 0 6 0 0 AS- i Profil S- BAE (62 slaves)	
R/ 1 0 7 0 <b>8</b> 0 6 0 0 AS- i S- 3.0 (31slaves)	
Heating module	
R/	
R/ 1 0 0 . <b>1</b> 6 0 0 With heating module 12 to 24 Vdc	
R/ 1 0 0 . <b>2</b> 6 0 0 With heating module 100 to 240 Vac	
Visualisation	
potyriole 3D	



Codification	Designation
	Configuration
R/ 0 6 <b>0</b> 0	Without
	Diagnosis
R/ 6 <b>0</b> 0	Without

## Distribution possibilities

Codification	Designation		
4/2 distributor monostable			
R/ <b>P</b> . 2 A	4/2 mono (On/Off) - Actair 3 to 200 "F" - FMC		
R/ <b>P</b> . 2 B	4/2 mono (On/Off) - Actair 3 to 200 "F" - OMC		
R/ <b>P</b> . 3 A	4/2 mono (On/Off) - Actair 3 to 200 "O" - FMC		
R/ <b>P</b> . 3 B	4/2 mono (On/Off) - Actair 3 to 200 "O" - OMC		
R/	4/2 mono (On/Off) - Actair 400 to 1600 - FMC		
R/ <b>P</b> . 4 B	4/2 mono (On/Off) - Actair 400 to 1600 - OMC		
R/ <b>P</b> . 6 A	4/2 mono (On/Off) - Dynactair 1,5 to 25 - FMA - FMC		
R/ <b>P</b> . 7 B	4/2 mono (On/Off) - Dynactair 1,5 to 25 - OMA - OMC		
R/ <b>P</b> . 8 A	4/2 mono (On/Off) - Dynactair 50 and 100 - FMA - FMC		
R/ <b>P</b> . 9 B	4/2 mono (On/Off) - Dynactair 50 and 100 - OMA - OMC		
R/ <b>P</b> . J A	· · · · · · · · · · · · · · · · · · ·		
R/ <b>P</b> . K B	4/2 mono (On/Off) - Dynactair 200 to 800 - OMA - OMC		
R/			
R/	4/2 mono (On/Off) - Actair NG 2 to NG 700 - OMC		
R/			
R/	4/2 mono (On/Off) - Dynactair NG 1 to NG 350 - OMA - OMC		
R/	1		
R/	4/2 mono (On/Off) - Quarter- turn actuator, single- acting		
R/	1		
R/	4/2 mono (On/Off) - Linear actuator, single- acting		
Distributor 4/2 bistable			
R/	4/2 bis (On/Off) - Actair 3 to 200 "F" - PIMC		
R/			
R/ <b>Q</b> . 4 D	4/2 bis (On/Off) - Actair 400 to 1600 - PIMC		
R/ <b>Q</b> . L D	4/2 bis (On/Off) - Actair NG 2 to NG 700 - PIMC		
R/			
R/ <b>Q</b> . Y D			



Codification	Designation		
4/3 distributor center closed			
R/			
R/			
R/ R . 2 C			
R/	4/3 cf (POS) - Actair 3 to 200 "O" - FMC		
R/			
R/ R . 3 C	4/3 cf (POS) - Actair 3 to 200 "O" - MPMC		
R/	4/3 cf (POS) - Actair 400 to 1600 - FMC		
R/	4/3 cf (POS) - Actair 400 to 1600 - OMC		
R/ R . 4 C	4/3 cf (POS) - Actair 400 to 1600 - MPMC		
R/ <b>R</b> 7 6 A	4/3 cf (POS) - Dynactair 1,5 to 25 - FMA - FMC		
R/	4/3 cf (POS) - Dynactair 1,5 to 25 - OMA - OMC		
R/ <b>R</b> 7 8 A	4/3 cf (POS) - Dynactair 50 and 100 - FMA - FMC		
R/ <b>R</b> 7 9 B	4/3 cf (POS) - Dynactair 50 and 100 - OMA - OMC		
R/ <b>R</b> 7 J A	4/3 cf (POS) - Dynactair 200 to 800 - FMA - FMC		
R/ <b>R</b> 7 K B	4/3 cf (POS) - Dynactair 200 to 800 - OMA - OMC		
R/ <b>R</b> 7 L A	4/3 cf (POS) - Actair NG 2 to NG 700 - FMC		
R/ <b>R</b> 7 L B	4/3 cf (POS) - Actair NG 2 to NG 700 - OMC		
R/ <b>R</b> 7 L C	4/3 cf (POS) - Actair NG 2 to NG 700 - MPMC		
R/	4/3 cf (POS) - Dynactair NG 1 to NG 350 FMA - FMC		
R/ <b>R</b> 7 N B	4/3 cf (POS) - Dynactair NG 1 to NG 350 - OMA - OMC		
R/	4/3 cf (POS) - Quarter- turn actuator, double- acting		
	4/3 cf (POS) - Quarter- turn actuator, double- acting - MPMC		
R/ <b>R</b> 7 X			
R/			
R/ <b>R</b> . Y C	4/3 cf (POS) - Linear actuator , double- acting - MPMC		
R/ <b>R</b> 7 Z	-		

## XI - Spare parts kit

Please contact us



## Notes: