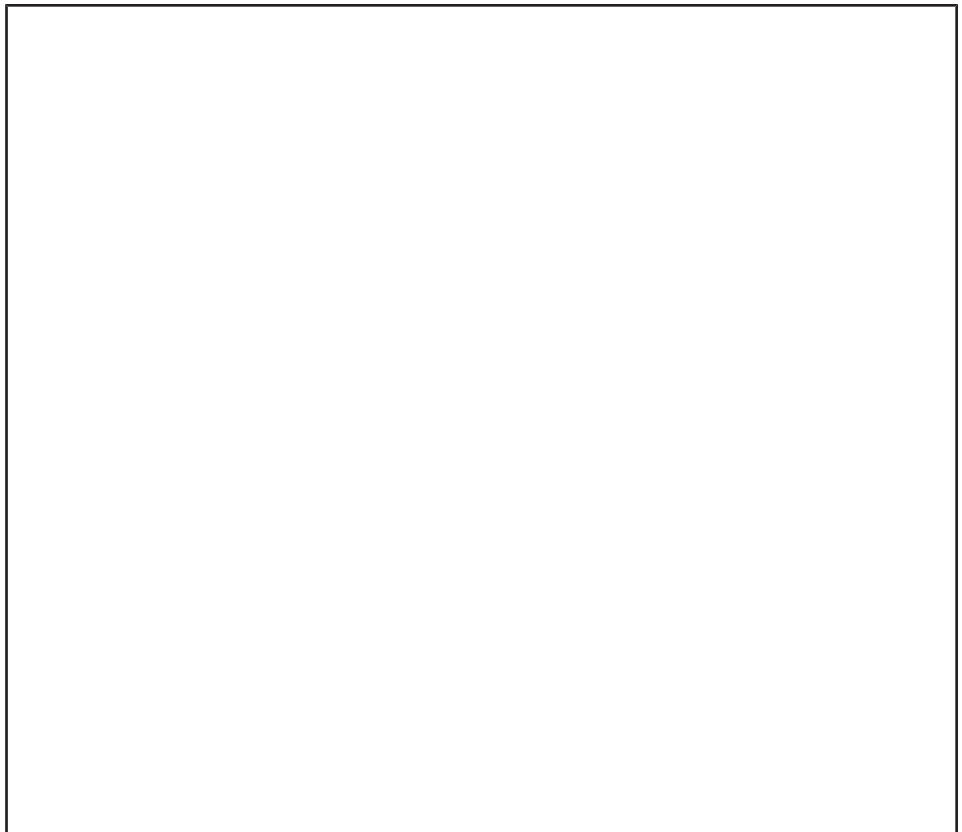


# Pump Power Monitoring

## Supplementary Operating Manual



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Supplementary Operating Manual Pump Power Monitoring

Original operating manual

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## 1 Supplementary Operating Manual

### 1.1 General

This supplementary operating manual accompanies the installation/operating manual. All information contained in the installation/operating manual must be observed.

**Table 1:** Relevant operating manuals

Type series	Reference number of the operating/installation manual
CPKN	2730.8, 2730.813
CPKN-CHs	2730.84
CPKNO	2730.88
Ecochem-Non-Seal	2940.8
Etanorm-R	1222.8
Etaline-R	1146.82
HPH	1122.8110
HPK	1221.8
HPK-L	1136.8
KWP	2361.8
KWP-Bloc	2362.8
Magnochem	2739.8, 2747.8
Magnochem-Bloc	2749.8, 2747.81
MegaCPK	2731.8
RPH	1316.8014
RPHb	1316.8012, 1316.9013
Secochem-Ex	2939.8
Secochem-Ex K	2939.81

### 1.2 Other applicable documents

Observe the accompanying product literature provided by the manufacturer of the load monitor.

### 1.3 Explosion protection

<b>Potentially explosive atmosphere</b>	The motor load monitor is approved for use in potentially explosive atmospheres.
<b>Monitoring of pump fill levels</b>	The dry running monitoring process as carried out by the motor load monitor is not realised in the context of Directive 94/9/EC (ATEX) for safeguarding a proper fill volume of the rotor space, as this would require the use of ATEX-certified monitoring equipment.

### 1.4 Function

The motor load monitor monitors the motor's active power input. The maximum and/or minimum power input can be adjusted by way of four potentiometers (ones and tens position). If the power rises above or falls below the set values, 2 LEDs will signal overload or low load. The respective output relay switches after an adjustable trip delay.

## 1.5 Application scenarios

**Table 2:** Possible application scenarios

Application	Type series	
	Magnochem	Secochem-Ex Ecochem Non Seal
Monitoring of plain bearings	X	X
Monitoring of rolling element bearings	X	-
Monitoring of minimum level	X	X
Monitoring of hydraulic overload/cavitation	X	X
Air in fluid handled	X	X
Coupling out of synchronisation	X	-

## 1.6 Technical data

**Table 3:** Technical data of motor load monitor

Characteristic	Value
Supply voltage	100 to 760 V
Voltage range	0.8 to 1.1 UN
Auxiliary voltage	AC 230 V
Frequency	50/60 Hz
Own consumption	≤ 4 VA
Setting range P1	0 to 7 tens position on relative scale 0 to 9 ones position
Setting range P2	0 to 7 tens position on relative scale 0 to 9 ones position
Measuring accuracy	± 4 % of full-scale value
Trip delay t v1 and t v2	1 to 10 s
Starting override t a	1 to 30 s
Input current range T1/k and L1/i	0.4 to 40 A <sup>1)</sup>
Overload capacity	
Max. continuous current I th	5 A per relay
Switching capacity of contacts to AC 15	3 A/AC 230 V IEC/EN 60947-5
Max. short-circuit protection, fuse	4 A gL to IEC/EN 60947-5-1
Temperature range	-20 to 55 °C
Climatic resistance	30/055/04 to IEC/EN 60068-1
Enclosure	IP40 housing IP20 terminals
Conductor connection	1 x 10 mm <sup>2</sup> solid or 1 x 6 mm <sup>2</sup> strand with sleeve
Quick-action fastening	DIN rail to IEC/EN 60715

1) Connect a current transformer in series for a higher nominal motor current.

### 1.7 Connecting the motor load monitor

1. Connect the power supply (AC 230 V) to terminals A1 and A3 (observe wiring diagrams).
2. Use terminals L/i and T/k as well as L1/i and T1/k to supply the motor current. Note the direction of the current in the process. An error message is output for reverse power (refer to the manufacturer's product literature).

**Phase testing** The measuring principle ( $P = V \times I \times \cos \varphi$ ) of the motor load monitor is only designed for the connection of a clockwise rotary field. If an anti-clockwise rotary field is present, phases L2/L3 must be interchanged at the motor load monitor so that a clockwise rotary field is reconnected to the monitor. If evaluation or analysis is still not possible, interchange the i/k connections.

### 1.8 Current transformer

If the nominal motor current exceeds 40 A, a current transformer must be connected in series.

Requirements for current transformer:

- Power to be transmitted: 2.5 VA
- Accuracy class: Class 0.5

Current transformers must not be earthed.

The current transformers listed below serve as a reference only.



#### NOTE

Select the transformer stage in line with the nominal motor current for integration of standardised motors with magnetic coupling and conventional pumps.

**Table 4:** Current transformer stages for Etaseco (DS)/Secochem-Ex/-K (DE) (for integration of a 5A transformer)



Motor size	Motor code	Voltage [V]			
		50 Hz		60 Hz	
		400	500	480	600
90.2	12M	-	-	-	-
	12	-	-	-	-
	22	-	-	-	-
112.2	42	-	-	-	-
	52	-	-	-	-
132.2	72	-	-	-	-
	112	-	-	-	-
	152	50	-	50	-
160.2	222	75	50	75	50
	302	100	75	100	75
200.2	402	150	100	150	100
	552	150	150	150	150

### 1.9 Rotate turn dial to home position

1. Rotate turn dial P<sub>1</sub> (tens position) all the way to the left (scale value 0).
2. Rotate turn dial P<sub>1</sub> (ones position) all the way to the left (scale value 0).
3. Rotate turn dial P<sub>2</sub> (tens position) all the way to the right (scale value 7).
4. Rotate turn dial P<sub>2</sub> (ones position) all the way to the right (scale value 10).

### 1.10 Setting the switching point for minimum power

When the switching point is undershot and the t<sub>i</sub> interval defined has elapsed, the motor is switched off.

	<p><b>NOTE</b></p> <p>Monitoring the "minimum power" also serves to switch off the pump should it run dry.</p>
	<p><b>CAUTION</b></p> <p><b>Operation at the throttling point for more than 5 minutes</b>        Damage to the pump (set)!</p> <p>▷ Always observe the minimum flow rate of the pump.</p>

1. Switch on the pump and check whether the green LED for  $V_N$  lights up (continuously).
2. Adjust the pump's flow rate to the desired minimum flow rate using the discharge-side shut-off element.  
Observe the power input, head and flow rate.
3. Turn or rotate potentiometer  $P_1$  in clockwise direction until the pump unit is switched off by the motor load monitor.
4. Open the discharge-side shut-off element and restart the pump.
5. Throttle the pump until it is switched off to check and verify the  $P_1$  setting.  
⇒ When the switching point coincides with the target minimum flow rate, the setting for the  $P_1$  turn dial is complete.
6. Using potentiometer  $t_a^{2)}$ , set the starting override to 10 sec. (recommended) to ensure that the increased input power of the motor at start-up is not taken into account.
7. Set potentiometer  $t_v^{2)}$  to a scale value of 5 sec. (recommended).
8. Restart the pump unit and immediately adjust to match the operating point.

### 1.11 Setting the switching point for maximum power

**Function** When the switching point is exceeded and the  $t_v$  interval defined has elapsed, the motor is switched off.

1. Adjust the pump's flow rate to the desired maximum flow rate using the discharge-side shut-off element.  
Observe the power input, head and flow rate.
2. Turn or rotate potentiometer  $t_{v2}$  all the way to the left (scale value 0.1).
3. Rotate turn dial  $P_2$  slowly in anti-clockwise direction until the pump unit is stopped.
4. Close the discharge-side shut-off element a little and start the pump unit.  
⇒ When the switching point coincides with the target maximum flow rate, the setting for the  $P_2$  turn dial is complete.
5. Restart the pump unit and immediately adjust to match the operating point.

2) When the pump is started, the  $t_a$  and  $t_v$  times set always total. The following calculation results when using the recommended values:  $t_a$  (10 sec.) +  $t_v$  (5 sec.) = 15 sec. During this time, the unit does not respond to the stop limits set. Time  $t_v$  remains active after time  $t_a$  has elapsed.



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